# ARRANGEMENTS OF HOMOTHETS OF A CONVEX BODY II 

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#### Abstract

A family of homothets of an $o$-symmetric convex body $K$ in $d$-dimensional Euclidean space is called a Minkowski arrangement if no homothet contains the center of any other homothet in its interior. We show that any pairwise intersecting Minkowski arrangement of a $d$ dimensional convex body has at most $2 \cdot 3^{d}$ members. This improves a result of Polyanskii (Discrete Mathematics 340 (2017), 1950-1956).

Using similar ideas, we also give a proof the following result of Polyanskii: Let $K_{1}, \ldots, K_{n}$ be a sequence of homothets of the $o$-symmetric convex body $K$, such that for any $i<j$, the center of $K_{j}$ lies on the boundary of $K_{i}$. Then $n=O\left(3^{d} d\right)$.


## 1. Introduction

We use the notation $[n]=\{1,2, \ldots, n\}$. A convex body $K$ in the $d$ dimensional Euclidean space $\mathbb{R}^{d}$ is a compact convex set with nonempty interior, and is o-symmetric if $K=-K$. A (positive) homothet of $K$ is a set of the form $\lambda K+v:=\{\lambda k+v: k \in K\}$, where $\lambda>0$ is the homothety ratio, and $v \in \mathbb{R}^{d}$ is a translation vector. If $K$ is $o$-symmetric, we also call $v$ the center of the homothet $\lambda K+v$. An arrangement of homothets of $K$ is a collection $\left\{\lambda_{i} K+v_{i}: i \in[n]\right\}$. A Minkowski arrangement of an $o$-symmetric convex body $K$ is a family $\left\{v_{i}+\lambda_{i} K\right\}$ of homothets of $K$ such that none of the homothets contains the center of any other homothet in its interior. This notion was introduced by L. Fejes Tóth [3] in the context of Minkowski's fundamental theorem on the minimal determinant of a packing lattice for a symmetric convex body, and was further studied by him in [4, 5], by Böröczky and Szabó in [2], and in connection with the Besicovitch covering theorem by Füredi and Loeb [6]. Recently, Minkowski arrangements have been used to study a problem arising in the design of wireless networks [9]. In [10] it was shown that the largest cardinality of a pairwise intersecting

[^0]Minkowski arrangement of homothets of an o-symmetric convex body in $\mathbb{R}^{d}$ is $O\left(3^{d} d \log d\right)$. This was improved to $3^{d+1}$ by Polyanskii [11]. We make the following slight improvement.

Theorem 1.1. For any o-symmetric convex body $K$ in $\mathbb{R}^{d}$, a pairwise intersecting Minkowski arrangement has at most $2 \cdot 3^{d}$ members.

Note that the $d$-cube has $3^{d}$ pairwise intersecting translates that form a Minkowski arrangement. The proof uses ideas from [7] and [8].

In [10], bounds on pairwise intersecting Minkowski arrangements were used to give an upper bound of $O\left(6^{d} d^{2} \log d\right)$ on the length of a sequence of homothets $v_{i}+\lambda_{i} K$ of an o-symmetric convex body $K$ such that $v_{j} \in$ $\operatorname{bd}\left(v_{i}+\lambda_{i} K\right)$ whenever $j>i$. This bound was improved to $O\left(3^{d} d\right)$ by Polyanskii [11]. We use some similar ideas to the proof of Theorem 1.1 to give a short proof of this result of Polyanskii.

Theorem 1.2 (Polyanskii [11]). Let $K$ be an o-symmetric convex body, and $v_{1}, v_{2}, \ldots, v_{n} \in \mathbb{R}^{d}$. Let $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{n-1}>0$, and assume that for any $1 \leq i<j \leq n$ we have $v_{j} \in \operatorname{bd}\left(v_{i}+\lambda_{i} K\right)$. Then $n=O\left(3^{d} d\right)$.

Clearly, when $K$ is the cube, $n=2^{d}$ is attained. It would be interesting to find better bounds for the maximum size of a family satisfying the conditions of Theorem 1.2.

The interest in this result is that it gives the upper bound $k^{O\left(3^{d} d\right)}$ to the cardinality of a set in a $d$-dimensional normed space in which only $k$ nonzero distances occur between pairs of points. This is currently the best known upper bound if $k=\Omega\left(3^{d} d\right)$ (see [12] for a survey of this problem).

## 2. Proof of Theorem 1.1

Theorem 2.1. Let $d \geq 1$. Suppose that there exists an o-symmetric convex body $K$ in $\mathbb{R}^{d}$ which has a pairwise intersecting Minkowski arrangement of $n$ homothets. Then there exists a set $\left\{x_{1}, \ldots, x_{n}\right\}$ of $n$ points in $\mathbb{R}^{d+1}$ such that $o \notin \operatorname{conv}\left\{x_{1}, \ldots, x_{n}\right\}$, and for any distinct $i, j \in[n], i<j$, there exists a nonzero linear functional $f_{i j}: \mathbb{R}^{d+1} \rightarrow \mathbb{R}$ with

$$
\begin{equation*}
\left|f_{i j}\left(x_{k}\right)\right| \leq\left|f_{i j}\left(x_{i}\right)-f_{i j}\left(x_{j}\right)\right| \quad \text { for all } k \in[n] \tag{2.1}
\end{equation*}
$$

We remark that the converse of the above theorem does not hold. We describe a simple counterexample for $d=1$. On the one hand, clearly, a pairwise intersecting Minkowski arrangement of intervals in $\mathbb{R}$ has at most two members. On the other hand, there is a set of 5 points on the plane satisfying the conclusion of Theorem 2.1. Indeed, let $\left\{x_{1}, \ldots, x_{5}\right\}$ be the vertex set of a regular pentagon, with o just outside the pentagon, close to the midpoint of an edge. It is easy to see that for any pair $x_{i}, x_{j}$ of vertices, there is a line through $o$ such that the projections $\pi\left(x_{k}\right)$ of the vertices onto the line are all within distance $\left|\pi\left(x_{i}\right)-\pi\left(x_{j}\right)\right|$ of $o$.

The above remark is to be contrasted with the equivalence in the following result, which generalizes part of Theorem 1.4 of [7].

Theorem 2.2. Given $\lambda \geq 1$, and $D \in \mathbb{Z}, D \geq 1$. Then the following statements are equivalent.
(i) There exists a set $\left\{x_{1}, \ldots, x_{n}\right\}$ of $n$ points in $\mathbb{R}^{D}$, such that $o \notin$ $\operatorname{conv}\left\{x_{1}, \ldots, x_{n}\right\}$, and for any distinct $i, j \in[n], i<j$ there exists a nonzero linear functional $f_{i j}: \mathbb{R}^{D} \rightarrow \mathbb{R}$ with

$$
\begin{equation*}
\left|f_{i j}\left(x_{k}\right)\right| \leq \frac{\lambda}{2}\left|f_{i j}\left(x_{i}\right)-f_{i j}\left(x_{j}\right)\right| \quad \text { for all } k \in[n] \tag{2.2}
\end{equation*}
$$

(ii) There is an o-symmetric convex set $L$ in $\mathbb{R}^{D}$ that has $n$ nonoverlapping translates $L+t_{1}, \ldots, L+t_{n}$, each intersecting $(\lambda-1) L$, with $o \notin \operatorname{conv}\left\{t_{1}, \ldots, t_{n}\right\}$.

We note that the equivalence between (ii) and (iv) of Theorem 1.4 in [7] is exactly the above theorem in the case $\lambda=1$.
Theorem 2.3. Let $K$ be an o-symmetric convex set in $\mathbb{R}^{D}$ with $D \geq 2$, and let $\alpha K+t_{1}, \ldots, \alpha K+t_{n}$ be $n$ nonoverlapping translates of $\alpha K$ with $\alpha>0$ such that each translate intersects $K$, and $o \notin \operatorname{int}\left(\operatorname{conv}\left\{t_{1}, \ldots, t_{n}\right\}\right)$. Then

$$
\begin{equation*}
n \leq \frac{(1+2 \alpha)^{D-1}(1+3 \alpha)}{2 \alpha^{D}} \tag{2.3}
\end{equation*}
$$

This theorem is a slight modification of Theorem 1.5 of [7]. There the translates of $\alpha K$ touch $K$, whereas here they may overlap with $K$. Theorem 2.3 is sharp for $\alpha=1$. Indeed, let $K$ be the cube $[-1,1]^{D}$, and consider the $2 \cdot 3^{D-1}$ translation vectors $\left\{t \in\{-2,0,2\}^{D}: t^{(1)} \geq t^{(2)}\right\}$.

Combining Theorems 2.1, 2.2, and 2.3 (with $\lambda=2, K=(\lambda-1) L=L$, $\alpha=1 /(\lambda-1)=1)$, we immediately obtain Theorem 1.1.

## 3. Proof of Theorem 2.1

Let the Minkowski arrangement be $\left\{v_{i}+\lambda_{i} K: i \in[n]\right\}$, where $\lambda_{i}>0$ and $v_{i} \in \mathbb{R}^{d}$ for each $i \in[n]$. Let $x_{i}=\left(\lambda_{i}^{-1} v_{i}, \lambda_{i}^{-1}\right) \in \mathbb{R}^{d} \times \mathbb{R}, i \in[n]$. Fix distinct $i, j \in\{1, \ldots, n\}$. We will find a linear $f: \mathbb{R}^{d} \times \mathbb{R} \rightarrow \mathbb{R}$ that satisfies (2.1). Let $\varphi: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a linear functional such that $\varphi(x) \leq\|x\|_{K}$ for all $x \in \mathbb{R}^{d}$ and $\varphi\left(v_{j}-v_{i}\right)=\left\|v_{j}-v_{i}\right\|_{K}$. (Thus, $\varphi^{-1}(1)$ is a hyperplane that supports $K$ at $\left\|v_{j}-v_{i}\right\|_{K}^{-1}\left(v_{j}-v_{i}\right)$.)

Since any two homothets $v_{k}+\lambda_{k} K$ and $v_{\ell}+\lambda_{\ell} K$ intersect, any two of the compact intervals $\varphi\left(v_{k}+\lambda_{k} K\right)$ and $\varphi\left(v_{\ell}+\lambda_{\ell} K\right)$ intersect in $\mathbb{R}$. By Helly's Theorem in $\mathbb{R}$, there exists $\alpha \in \bigcap_{t=1}^{n} \varphi\left(v_{t}+\lambda_{t} K\right)$. Since $\varphi\left(v_{i}+\lambda_{i} K\right)=$ $\left[\varphi\left(v_{i}\right)-\lambda_{i}, \varphi\left(v_{i}\right)+\lambda_{i}\right]$ and $\varphi\left(v_{j}+\lambda_{j} K\right)=\left[\varphi\left(v_{j}\right)-\lambda_{j}, \varphi\left(v_{j}\right)+\lambda_{j}\right]$, we have

$$
\varphi\left(v_{j}\right)-\lambda_{j} \leq \alpha \leq \varphi\left(v_{i}\right)+\lambda_{i}
$$

By the Minkowski property,

$$
\varphi\left(v_{j}-v_{i}\right)=\left\|v_{j}-v_{i}\right\|_{K} \geq \max \left\{\lambda_{i}, \lambda_{j}\right\} .
$$

It follows that

$$
\begin{equation*}
\varphi\left(v_{i}\right) \leq \alpha \leq \varphi\left(v_{j}\right) \tag{3.1}
\end{equation*}
$$

We set $f=(\varphi,-\alpha) \in\left(\mathbb{R}^{d} \times \mathbb{R}\right)^{*}$, that is, define $f(x)=\varphi(v)-\alpha \mu$, where $x=(v, \mu) \in \mathbb{R}^{d} \times \mathbb{R}$. We show that $f\left(x_{j}-x_{i}\right) \geq 1$, and $\left|f\left(x_{k}\right)\right| \leq 1$ for all $k \in\{1, \ldots, n\}$. This will show that (2.1) is satisfied, which will finish the proof.

$$
\begin{aligned}
f\left(x_{j}-x_{i}\right) & =\varphi\left(\lambda_{j}^{-1} v_{j}-\lambda_{i}^{-1} v_{i}\right)-\alpha\left(\lambda_{j}^{-1}-\lambda_{i}^{-1}\right) \\
& =\frac{\varphi\left(v_{j}\right)-\alpha}{\lambda_{j}}+\frac{\alpha-\varphi\left(v_{i}\right)}{\lambda_{i}} \\
& \stackrel{(3.1)}{\geq} \frac{\varphi\left(v_{j}\right)-\alpha+\alpha-\varphi\left(v_{i}\right)}{\max \left\{\lambda_{i}, \lambda_{j}\right\}} \\
& =\frac{\left\|v_{j}-v_{i}\right\|_{K}}{\max \left\{\lambda_{i}, \lambda_{j}\right\}} \geq 1 .
\end{aligned}
$$

Since $\alpha \in \varphi\left(v_{k}+\lambda_{k} K\right)$, there exists $x \in K$ such that $\varphi\left(v_{k}+\lambda_{k} x\right)=\alpha$. Therefore,

$$
\left|f\left(x_{k}\right)\right|=\left|\varphi\left(\lambda_{k}^{-1} v_{k}\right)-\alpha \lambda_{k}^{-1}\right|=|\varphi(x)| \leq\|x\|_{K} \leq 1
$$

## 4. Proof of Theorem 1.2

The following proof is very similar to the proof of Theorem 2.1.
Without loss of generality, $\min _{i} \lambda_{i}=1$. Denote the unit ball of $\|\cdot\|$ by $K$. Let $x_{i}=\left(\lambda_{i}^{-1} v_{i}, \lambda_{i}^{-1}\right) \in \mathbb{R}^{d} \times \mathbb{R}, i=1, \ldots, n-1$. Let $N \geq 1$, to be fixed later. For each $m=0, \ldots, N$, let

$$
X_{m}=\left\{x_{i}: i \in[n-1],\left\lfloor N \log _{2} \lambda_{i}\right\rfloor \equiv m(\bmod N+1)\right\} .
$$

Then $X_{0}, \ldots, X_{N}$ partition $\left\{x_{1}, \ldots, x_{n-1}\right\}$ into $N+1$ parts. Fix $x_{i}, x_{j} \in X_{m}$ such that $1 \leq i<j<n$. We will find a linear $f: \mathbb{R}^{d} \times \mathbb{R} \rightarrow \mathbb{R}$ such that (2.2) is satisfied for all $x_{k} \in X_{m}$ and $\lambda=2-2^{1 / N}$. Let $\varphi: \mathbb{R}^{d} \rightarrow \mathbb{R}$ be a linear functional such that $\varphi(v) \leq\|v\|$ for all $v \in \mathbb{R}^{d}$ and

$$
\begin{equation*}
\varphi\left(v_{j}-v_{i}\right)=\left\|v_{j}-v_{i}\right\|=\lambda_{i} . \tag{4.1}
\end{equation*}
$$

(Thus, $\varphi^{-1}(1)$ is a hyperplane that supports $K$ at $\left\|v_{j}-v_{i}\right\|_{K}^{-1}\left(v_{j}-v_{i}\right)$.)
Since any two homothets $v_{k}+\lambda_{k} K$ and $v_{\ell}+\lambda_{\ell} K$ intersect in their interiors, any two of the open intervals $\varphi\left(v_{k}+\lambda_{k}\right.$ int $\left.K\right)$ and $\varphi\left(v_{\ell}+\lambda_{\ell}\right.$ int $\left.K\right)$ intersect in $\mathbb{R}$. By Helly's Theorem in $\mathbb{R}$, there exists $\alpha \in \bigcap_{t=1}^{n} \varphi\left(v_{t}+\lambda_{t} \operatorname{int} K\right)$. Since $\varphi\left(v_{i}+\lambda_{i}\right.$ int $\left.K\right)=\left(\varphi\left(v_{i}\right)-\lambda_{i}, \varphi\left(v_{i}\right)+\lambda_{i}\right)$ and $\varphi\left(v_{j}+\lambda_{j} \operatorname{int} K\right)=$ ( $\left.\varphi\left(v_{j}\right)-\lambda_{j}, \varphi\left(v_{j}\right)+\lambda_{j}\right)$, we have

$$
\varphi\left(v_{j}\right)-\lambda_{j}<\alpha<\varphi\left(v_{i}\right)+\lambda_{i} .
$$

By (4.1), we can rewrite this as

$$
\begin{equation*}
-\lambda_{i}<\varphi\left(v_{i}\right)-\alpha<\lambda_{j}-\lambda_{i} . \tag{4.2}
\end{equation*}
$$

We set $f=(\varphi,-\alpha) \in\left(\mathbb{R}^{d} \times \mathbb{R}\right)^{*}$, that is, for $x=(v, \mu) \in \mathbb{R}^{d} \times \mathbb{R}$, we let $f(x)=\varphi(v)-\alpha \mu$. It remains to show that $f\left(x_{j}-x_{i}\right)>2-2^{1 / N}$, and $\left|f\left(x_{k}\right)\right| \leq 1$ for all $k \in\{0, \ldots, n\}$, since this will show that (2.2) is satisfied
with $\lambda=2-2^{1 / N}$. By applying Theorems 2.2 and 2.3 with $\lambda=2 /(2-$ $\left.2^{1 / N}\right)=2+\frac{\log 4}{N}+O\left(N^{-2}\right), K=(\lambda-1) L$ and $\alpha=1 /(\lambda-1)=2^{1-1 / N}-1$, we obtain $\left|X_{m}\right| \leq(1+\lambda / 2)(1+\lambda)^{d}$, and it follows that

$$
n-1 \leq(N+1)(1+\lambda / 2)(1+\lambda)^{d}
$$

If we choose $N=d$, we obtain $\lambda=2+\frac{\log 4}{d}+O\left(d^{-2}\right)$ and $n=3^{d} O(d)$, which would finish the proof.

By definition of $X_{m}$,

$$
\left\lfloor N \log _{2} \lambda_{j}\right\rfloor-\left\lfloor N \log _{2} \lambda_{i}\right\rfloor=k N \quad \text { for some } k \in \mathbb{Z}
$$

If $k \geq 1$, then $N \log _{2} \lambda_{j}-N \log _{2} \lambda_{i}>N$, hence $\lambda_{j} / \lambda_{i}>2$. However, we also have

$$
\lambda_{i}=\left\|v_{i}-v_{j}\right\| \geq\left\|v_{j}-v_{n}\right\|-\left\|v_{n}-v_{i}\right\|=\lambda_{j}-\lambda_{i}
$$

a contradiction. Therefore, $k \leq 0$, that is, $\left\lfloor N \log _{2} \lambda_{j}\right\rfloor-\left\lfloor N \log _{2} \lambda_{i}\right\rfloor \leq 0$. This gives $N \log _{2} \lambda_{j}-N \log _{2} \lambda_{i}<1$ and

$$
\begin{equation*}
\frac{\lambda_{j}}{\lambda_{i}}<2^{1 / N} \tag{4.3}
\end{equation*}
$$

It follows that

$$
\begin{aligned}
f\left(x_{j}-x_{i}\right) & =\varphi\left(\lambda_{j}^{-1} v_{j}-\lambda_{i}^{-1} v_{i}\right)-\alpha\left(\lambda_{j}^{-1}-\lambda_{i}^{-1}\right) \\
& =\frac{\varphi\left(v_{j}\right)-\alpha}{\lambda_{j}}+\frac{\alpha-\varphi\left(v_{i}\right)}{\lambda_{i}} \\
& =\frac{\varphi\left(v_{i}\right)+\lambda_{i}-\alpha}{\lambda_{j}}+\frac{\alpha-\varphi\left(v_{i}\right)}{\lambda_{i}} \\
& \stackrel{(4.2),(4.3)}{>} \frac{2^{-1 / N}\left(\varphi\left(v_{i}\right)+\lambda_{i}-\alpha\right)+\alpha-\varphi\left(v_{i}\right)}{\lambda_{i}} \\
& =2^{-1 / N}+\frac{\left(1-2^{-1 / N}\right)\left(\alpha-\varphi\left(v_{i}\right)\right)}{\lambda_{i}} \\
& \stackrel{(4.2)}{>} 2^{-1 / N}+\frac{\left(1-2^{-1 / N}\right)\left(\lambda_{i}-\lambda_{j}\right)}{\lambda_{i}} \\
& =1-\left(1-2^{-1 / N}\right) \frac{\lambda_{j}}{\lambda_{i}} \\
& \stackrel{(4.2)}{>} 1-\left(1-2^{-1 / N}\right) 2^{1 / N} \\
& =2-2^{1 / N}
\end{aligned}
$$

Since $\alpha \in \varphi\left(v_{k}+\lambda_{k} K\right)$, there exists $x \in K$ such that $\varphi\left(v_{k}+\lambda_{k} x\right)=\alpha$. Therefore,

$$
\left|f\left(x_{k}\right)\right|=\left|\varphi\left(\lambda_{k}^{-1} v_{k}\right)-\alpha \lambda_{k}^{-1}\right|=|\varphi(x)| \leq\|x\|_{K} \leq 1
$$

## 5. Proof of Theorem 2.2

Assume that (i) holds. Let $C:=\bigcap_{i \neq j} S_{i j}$ be the intersection of the $o$-symmetric slabs $S_{i j}:=\left\{p \in \mathbb{R}^{D}:\left|f_{i j}(p)\right| \leq \frac{\lambda}{2}\left|f_{i j}\left(x_{i}\right)-f_{i j}\left(x_{j}\right)\right|\right\}$. By assumption, $C \supseteq\left\{x_{1}, \ldots, x_{n}\right\}$. For each $i \in[n]$, let $C_{i}:=\frac{\lambda x_{i}+C}{\lambda+1}$ be the homothetic copy of $C$ with center of homothety $x_{i}$, and of ratio $\frac{1}{\lambda+1}$. It is an easy exercise that the $C_{i} \mathrm{~s}$ are nonoverlapping. Moreover, by the symmetry of $C$, we have $\frac{\lambda-1}{\lambda+1} x_{i} \in C_{i} \cap \frac{\lambda-1}{\lambda+1} C$. Thus, for $L:=\frac{1}{\lambda+1} C$, and $t_{i}:=\frac{\lambda}{\lambda+1} x_{i}$, (ii) holds as promised.

Next, assume that (ii) holds. Fix $i, j \in[n], i \neq j$. Since $L+t_{i}$ and $L+t_{j}$ are nonoverlapping, there is a linear functional $f$ such that the two real intervals $s_{i}:=f\left(L+t_{i}\right)$ and $s_{j}:=f\left(L+t_{i}\right)$ do not overlap. These two intervals are of equal length, which we denote by $w$. Thus, we have

$$
\begin{equation*}
w \leq\left|f\left(t_{i}\right)-f\left(t_{j}\right)\right| \tag{5.1}
\end{equation*}
$$

On the other hand, $s_{k}:=f\left(L+t_{k}\right)$ is also a real interval of length $w$ for any $k \in[n]$; and $s_{0}:=f((\lambda-1) L)$ is a 0 -symmetric real interval of length $(\lambda-1) w$, which intersects each $s_{k}$. Thus, for the center $f\left(t_{k}\right)$ of $s_{k}$, we have $\left|f\left(t_{k}\right)\right| \leq \frac{(\lambda-1) w}{2}+\frac{w}{2}=\frac{\lambda w}{2}$. Now, (5.1) yields $\left|f\left(t_{k}\right)\right| \leq \frac{\lambda}{2}\left|f\left(t_{i}\right)-f\left(t_{j}\right)\right|$. Thus, we may set $f_{i j}:=f$. This argument is valid for any $i$ and $j$, thus, with $x_{i}:=t_{i}$, we obtain (i).

## 6. Proof of Theorem 2.3

The proof is an almost verbatim copy of the proof of Theorem 1.5 of [7]. There are two points of difference, which we will note.

We recall Lemma 3.1 of [7], which is a slightly more general version of the Lemma of [1].
Lemma 6.1. Let $f$ be a function on $[0,1]$ with the properties $f(0) \geq 0, f$ is positive and monotone increasing on $(0,1]$, and $f(x)=(g(x))^{k}$ for some concave function $g$ and $k>0$. Then

$$
F(y):=\frac{1}{f(y)} \int_{0}^{y} f(x) \mathrm{d} x
$$

is strictly increasing on $(0,1]$.
Proof of Theorem 2.3. Clearly, we may assume that $K$ is bounded, otherwise, by a projection, we can reduce the dimension. Let $\alpha K+t_{1}, \alpha K+$ $t_{2}, \ldots, \alpha K+t_{n}$ be pairwise nonoverlapping translates of $\alpha K$ that intersect $K$. By the assumptions of the theorem, there is a nonzero vector $v \in \mathbb{R}^{D}$ such that $a_{i}:=\left\langle t_{i}, v\right\rangle \geq 0$ for $i \in[n]$. Set $h(x):=\left\{p \in \mathbb{R}^{D}:\langle p, v\rangle=x\right\}$. Without loss of generality, we may assume that $h(-1)$ and $h(1)$ are supporting hyperplanes of $K$.

Clearly, $\alpha K+t_{i}$ is between $h(-\alpha)$ and $h(1+2 \alpha)$, and it is contained in $(1+2 \alpha) K$, for $i \in[n]$.

$$
\begin{align*}
& \int_{-\alpha}^{1+2 \alpha} \mathrm{~V}_{D-1}\left(\left(\bigcup_{i=1}^{n} \alpha K+t_{i}\right) \cap h(x)\right) \mathrm{d} x=n \alpha^{D} \mathrm{~V}_{D}(K)  \tag{6.1}\\
& \int_{0}^{1+2 \alpha} \mathrm{~V}_{D-1}\left(\left(\bigcup_{i=1}^{n} \alpha K+t_{i}\right) \cap h(x)\right) \mathrm{d} x  \tag{6.2}\\
& \leq \int_{0}^{1+2 \alpha} \mathrm{~V}_{D-1}((1+2 \alpha) K \cap h(x)) \mathrm{d} x=\frac{(1+2 \alpha)^{d}}{2} \mathrm{~V}_{D}(K) .
\end{align*}
$$

We note that this was the first point of difference from the proof in [7]: here, we do not subtract the contribution of $K$ in the total volume on the right hand side of the inequality.

Set $f(x):=\mathrm{V}_{D-1}(\alpha K \cap h(x-\alpha))$, and observe that the conditions of Lemma 6.1 are satisfied by $f$ (with $k=D-1$, by the Brunn-Minkowski inequality). We may assume that $a_{1}, \ldots, a_{m} \leq \alpha<a_{m+1}, \ldots, a_{n}$. By Lemma 6.1,

$$
\begin{aligned}
& \int_{-\alpha}^{0} \mathrm{~V}_{D-1}\left(\left(\bigcup_{i=1}^{n}\left(\alpha K+t_{i}\right)\right) \cap h(x)\right) \mathrm{d} x=\sum_{i=1}^{m} \int_{0}^{\alpha-a_{i}} f(x) \mathrm{d} x \\
\leq & \sum_{i=1}^{m} \int_{0}^{\alpha} f(x) \mathrm{d} x \frac{f\left(\alpha-a_{i}\right)}{f(\alpha)}=\frac{\alpha^{d} \mathrm{~V}_{D}(K)}{2 f(\alpha)} \sum_{i=1}^{m} \mathrm{~V}_{D-1}\left(\left(\alpha K+t_{i}\right) \cap h(0)\right) \\
= & \frac{\alpha^{d} \mathrm{~V}_{D}(K)}{2 f(\alpha)} \mathrm{V}_{D-1}\left(\left(\bigcup_{i=1}^{m}\left(\alpha K+t_{i}\right)\right) \cap h(0)\right) \\
\leq & \frac{\alpha^{d} \mathrm{~V}_{D}(K)}{2 f(\alpha)}\left[\mathrm{V}_{D-1}((1+2 \alpha) K \cap h(0))\right]=\frac{\alpha(1+2 \alpha)^{D-1}}{2} \mathrm{~V}_{D}(K) .
\end{aligned}
$$

We note that this was the second point of difference from the proof in [7]: again, the contribution of $K$ to the volume is not subtracted.

This inequality, combined with (6.1) and (6.2), yields (2.3).

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